

# Scheduling in data gathering networks with variable communication speed and a processing stage

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- 1 Introduction
- 2 Computational complexity
- 3 Heuristics & computational experiments
- 4 Conclusions

Data gathering applications:

- wireless sensor networks
- collecting results of distributed computations

Changing communication speed:

- other users/applications sharing the network
- maintenance activities

# Data gathering network

- A set of  $m$  worker nodes  $P_1, \dots, P_m$  are connected to a single base station.
- Node  $P_i$  holds dataset  $D_i$  of size  $\alpha_i$  that has to be transferred to the base station for processing.
- Sending data of size  $\alpha$  over a free link between  $P_i$  and the base station takes time  $c_i\alpha$ .
- Processing dataset  $D_i$  requires time  $a\alpha_i$ .
- At most one node can communicate with the base station at a time and at most one dataset can be processed at a time.
- Preemptions are allowed.

# Communication speed changes

- Background communications may degrade the link performance.
- If the link between  $P_i$  and the base station is loaded, data of size  $\alpha$  is transferred in time  $\delta c_i \alpha$ , for some given  $\delta > 1$ .
- Hence, the maximum time that may be necessary to gather all data is 
$$\overline{T_c} = \delta \sum_{i=1}^m c_i \alpha_i$$
- The link between  $P_i$  and the base station is loaded in  $n_i$  given disjoint time intervals  $[t'_{ij}, t''_{ij}]$ , where  $j = 1, \dots, n_i$ ,  $t'_{ij} < \overline{T_c}$ .

# Scheduling problem

Given:

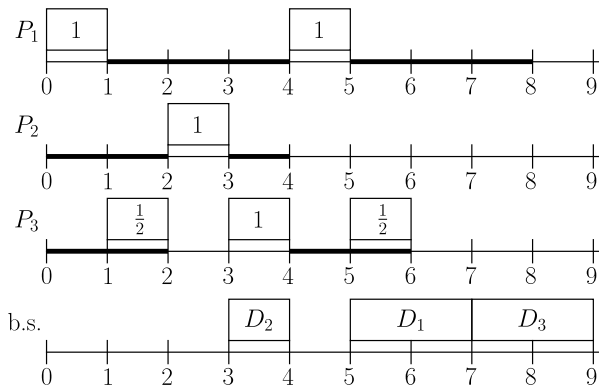
- number of workers  $m$ ,
- link parameters  $c_i$ , for  $1 \leq i \leq m$ ,
- link degradation parameter  $\delta$ ,
- $n = n_1 + \dots + n_m$  loaded intervals  $[t'_{ij}, t''_{ij}]$ , where  $i = 1, \dots, m$ ,  
 $j = 1, \dots, n_i$ ,
- base station parameter  $a$ ,

minimize the total time  $T$  required to gather and process all data.

# Example

$$m = 3, \quad \delta = 2, \quad c_1 = c_2 = c_3 = a = 1$$

$$\alpha_1 = 2, \quad \alpha_2 = 1, \quad \alpha_3 = 2$$



- It can be assumed without loss of generality that:
  - the communication network is never idle before transferring all data,
  - datasets are processed in the order in which they arrive at the base station.
- If  $a = 0$ , the problem can be solved in polynomial time using linear programming (Berlińska, 2016).
- If  $a = 0$  and communication preemptions are not allowed, the problem is strongly NP-hard (Berlińska, 2018).



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## Proposition 1

The analyzed scheduling problem is strongly NP-hard, even if  $a = 1$  and  $c_i = 1$  for  $i = 1, \dots, m$ .

Proof: reduction from the 3-Partition problem.

## 3-Partition

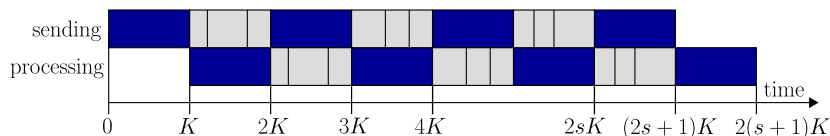
Given a positive integer  $K$  and a set of  $3s$  positive integers  $\{x_1, \dots, x_{3s}\}$  such that  $K/4 < x_j < K/2$  for each  $j \in \mathcal{S} = \{1, 2, \dots, 3s\}$ , and  $\sum_{j=1}^{3s} x_j = sK$ , is it possible to partition the index set  $\mathcal{S}$  into  $s$  disjoint sets  $\mathcal{S}_1, \mathcal{S}_2, \dots, \mathcal{S}_s$  such that for each  $1 \leq i \leq s$ ,  $\sum_{j \in \mathcal{S}_i} x_j = K$ ?

Instance construction:

- $m = 4s + 1$
- $c_i = 1$  for all  $i$ ,  $a = 1$
- $3s$  “regular” datasets with  $\alpha_i = x_i$  for  $i = 1, \dots, 3s$
- $s + 1$  “blocker” datasets with  $\alpha_i = K$  for  $i = 3s + 1, \dots, 4s + 1$
- the links used by nodes  $P_1, \dots, P_{3s}$  are always free
- the links used by nodes  $P_{3s+1}, \dots, P_{4s+1}$  are loaded in time intervals  $[(2j - 1)K, 2jK)$  for  $j = 1, \dots, s + 1$
- $T = (2s + 2)K$

# Complexity: general case

3-Partition  $\Rightarrow$  schedule:

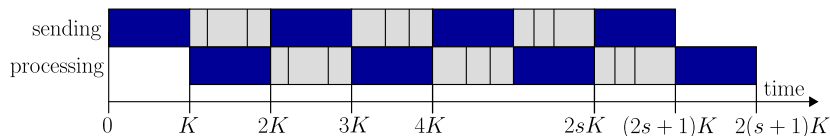


no 3-Partition  $\Rightarrow$  no schedule:

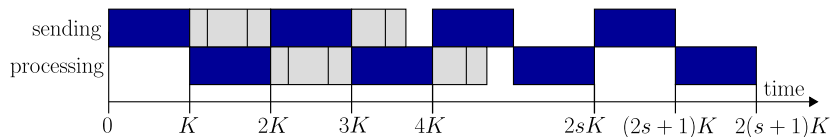
- Minimum communication idle time in interval  $[0, T)$  is  $K \Rightarrow$  all transfers have to use free links only.
- No data processed in interval  $[0, K) \Rightarrow$  there can be no processing idle times after time  $K$ .

# Complexity: general case

3-Partition  $\Rightarrow$  schedule:

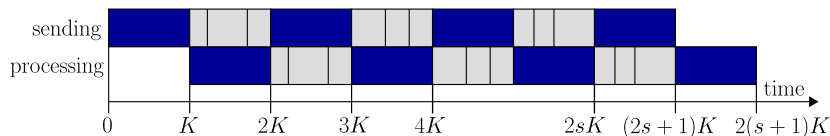


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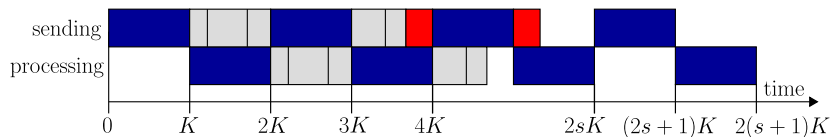


# Complexity: general case

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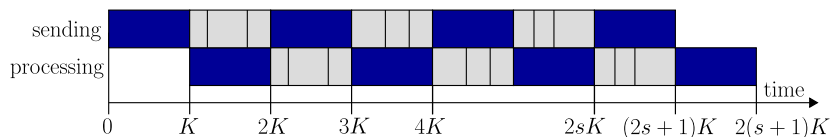


no 3-Partition  $\Rightarrow$  no schedule:

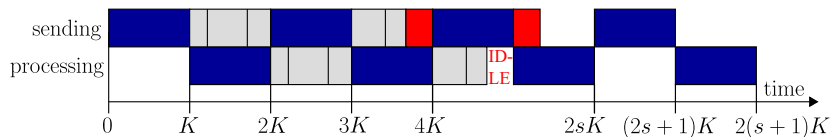


# Complexity: general case

3-Partition  $\Rightarrow$  schedule:



no 3-Partition  $\Rightarrow$  no schedule:



The following special cases can be solved in polynomial time

- 1  $n = 0 \Rightarrow F2|pmtn|C_{max}$ , Johnson's rule (Johnson, 1954)
- 2  $a = 0 \Rightarrow$  linear programming (Berlińska, 2016)
- 3  $a \leq c_i$  for all  $i$ , all links loaded in the same intervals (this work)
- 4  $a \geq \delta c_i$  for all  $i$ , all links loaded in the same intervals (this work)



## Towards polynomial cases (3) and (4)

### Lemma 1

If all links are loaded in the same intervals, then the time required to transfer a given set of datasets  $\{D_{i_1}, \dots, D_{i_k}\}$ , starting at time 0, does not depend on the order of communications.

Proof:

- Sending data of size  $\alpha$  at unit communication time  $c$  is equivalent to sending data of size  $c\alpha$  at unit communication time 1.
- If all links are loaded in the same intervals, sending datasets  $D_{i_1}, \dots, D_{i_k}$  over the respective links is equivalent to sending a single dataset of size  $\sum_{j=1}^k c_{i_j} \alpha_{i_j}$  over a link with communication speed 1 in the free intervals and  $1/\delta$  in the loaded intervals.

## Towards polynomial cases (3) and (4)

### Lemma 2

If all links are loaded in the same intervals, there exists an optimum non-preemptive schedule.

Proof:

- Suppose dataset  $D_i$  is transferred in several pieces in an optimum schedule  $\Sigma$ .
- Construct a new schedule  $\Sigma'$  by moving all messages containing parts of  $D_i$  just before its last piece. The other communications preceding the transfer of  $D_i$  are moved to the left.
- By Lemma 1,  $\Sigma'$  is not longer than  $\Sigma$ .
- Repeat until there are no preemptions.

### Proposition 2

If  $a \leq c_i$  for all  $i$ , and all links are loaded in the same intervals, then the optimum schedule can be constructed in  $O(m \log m + n)$  time by sending the datasets in the order of non-increasing sizes  $\alpha_i$ .

Proof:

- By Lemma 2, it is enough to consider non-preemptive schedules.
- Start with an optimum schedule  $\Sigma$  such that  $D_i$  is sent just before  $D_j$ , and  $\alpha_i < \alpha_j$ .
- Show that swapping  $D_i$  and  $D_j$  does not increase schedule length (Lemma 1 + calculations).
- Repeat.

## Proposition 3

If  $a \geq \delta c_i$  for all  $i$ , and all links are loaded in the same intervals, then the optimum schedule can be constructed in  $O(m \log m + n)$  time by sending the datasets in the order of non-decreasing  $c_i \alpha_i$ .

Proof:

- By Lemma 2, it is enough to consider non-preemptive schedules.
- Start with an optimum schedule  $\Sigma$  such that  $D_i$  is sent just before  $D_j$ , and  $c_i \alpha_i > c_j \alpha_j$ .
- Show that swapping  $D_i$  and  $D_j$  does not increase schedule length (Lemma 1 + calculations).
- Repeat.

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## Proposition 4

Constructing an optimum schedule for the analyzed problem may require preempting a dataset transfer at a time when no link speed changes.

Proof: Let  $m = 2$ ,  $c_1 = c_2 = 1$ ,  $a = 0$ ,  $\alpha_1 = \alpha_2 = 2$ . Suppose the first link is loaded in interval  $[2, 3)$ , and the second link is loaded in interval  $[3, 4)$ . The optimum schedule length 4 can be achieved only if all data are transferred over free links. This is not possible if no preemption takes place before time 2.

# Heuristic algorithms

Greedy heuristics running in  $O((m+n)^2)$  time: every time a dataset transfer completes or the speed of some link changes, the dataset to be transferred is selected according to a given rule.

- *gTime* chooses the dataset whose transfer will complete in the shortest time;
- *gRate* selects the dataset which will be sent at the best average communication rate (under the assumption that there will be no preemption);
- *gJohnson* associates with each available dataset a job consisting of two operations: sending the remaining part of this dataset, and processing this dataset, then chooses the best job using Johnson's rule.

# Test instances

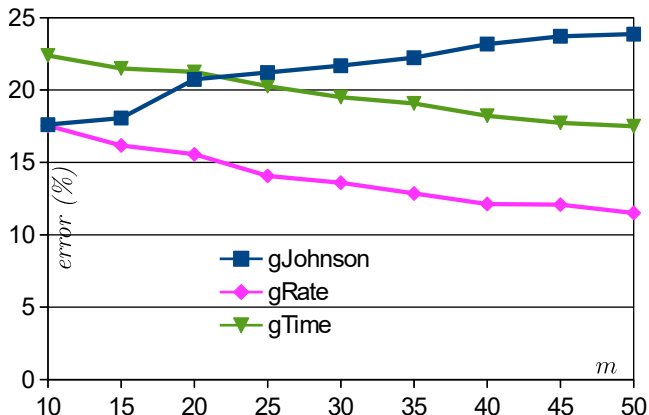
- $m \in \{10, 15, \dots, 50\}$
- $\alpha_i$  chosen randomly from the range  $[1, 20]$
- $\delta = 2$
- $c_i = c$  for  $i = 1, \dots, m$ ,  $c \in \{0.5, 0.75, 1\}$ ,  $a = 1$ ,  
representing the three cases of  $\delta c \leq a$ ,  $c < a < \delta c$  and  $a \leq c$
- for given  $F, L \in \{1, 5\}$ , the lengths of consecutive free and loaded intervals chosen randomly from the ranges  $[0, \frac{F}{m} \sum_{i=1}^m c_i \alpha_i]$  and  $[0, \frac{L}{m} \sum_{i=1}^m c_i \alpha_i]$  correspondingly, independently for each link, until reaching the communication time horizon  $\overline{T_c}$



# Measure of schedule quality

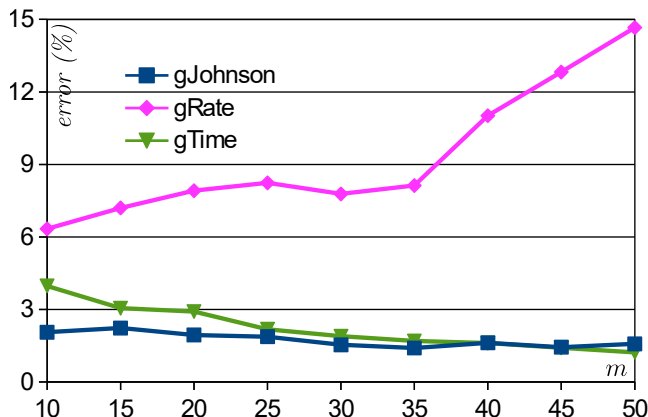
- Let  $T_c^{(i)}$  be the time required to transfer dataset  $D_i$  (starting at time 0), and let  $T_c$  be the minimum time necessary for transferring all data to the base station.
- Let  $T_J$  be the minimum time required for transferring and processing all datasets under the assumption that the communication links are always free.
- Schedule quality was measured by the average percentage error with respect to the lower bound  $LB = \max\{LB_1, LB_2, T_J\}$ , where
  - $LB_1 = \max_{i=1}^m \{T_c^{(i)} + a\alpha_i\}$
  - $LB_2 = T_c + \min_{i=1}^m \{a\alpha_i\}$

## Results vs. $m$ for $c = 1, F = 1, L = 1$



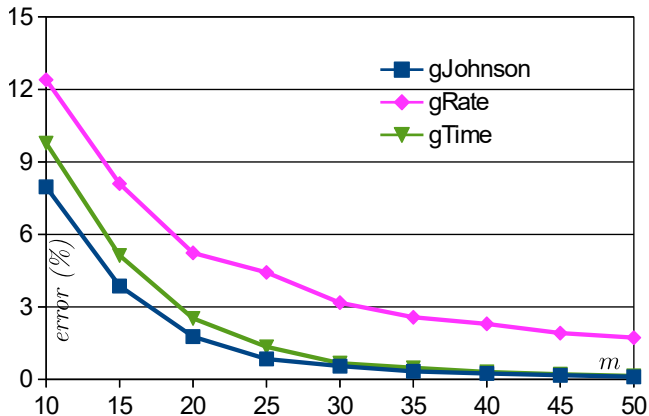
- Best results obtained by  $gRate$ .
- Results of  $gRate$  and  $gTime$  improve with growing  $m$ ,  $gJohnson$  performs worse for larger  $m$ .

## Results vs. $m$ for $c = 1, F = 5, L = 1$



- Best results obtained by  $gJohnson$  for  $m \leq 45$  and  $gTime$  for  $m = 50$ .
- Results of  $gJohnson$  and  $gTime$  improve with growing  $m$ ,  $gRate$  performs worse for larger  $m$ .

## Results vs. $m$ for $c = 0.75$ , $F = 1$ , $L = 1$



- Best results obtained by  $gJohnson$ .
- Results of all algorithms improve with growing  $m$ .

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# Conclusions

- We analyzed minimizing the time of data gathering in networks with variable communication speed and a processing stage.
- The problem is strongly NP-hard.
- Several polynomially-solvable cases were identified.
- Three greedy heuristics were proposed.
- Computational experiments showed that  $gRate$  is the best choice when communication is slow and the links are rarely free, but in other settings  $gJohnson$  and  $gTime$  are better.
- Future research: analysis of further special cases.